

MOTORI

$$\bar{I}_{1m} = \bar{I}_0 + \bar{I}_{12} \quad \bar{I}_{1\omega} = \bar{I}_0 + \bar{I}_{12\omega} \quad \bar{I}_{1cc} = \bar{I}_0 + \bar{I}_{1cc} \quad I_{12} = \frac{SV_1}{\sqrt{3} R_{12}} \quad I_{12} = \sqrt{\frac{S \cdot P_t}{3 R_{12}}}$$

$$I_{12} = \frac{V_{1m}}{\sqrt{\left(R_{11} + \frac{R_{12}}{s}\right)^2 + X^2}}$$

$$I_{12} = \sqrt{\frac{P_e P}{3R}} \quad \bar{I}_{12} = \bar{I}_1 - \bar{I}_0 \text{ per } s=1 \quad \bar{I}_{12} = \bar{I}_{12cc}$$

$$I_1 = \frac{P_a}{\sqrt{3} V_{1m}}$$

$$s=0 \quad I_{12} = I_{12\omega} \Rightarrow R_{12} \rightarrow 0 \quad I_{12} = \sqrt{\frac{5 \Omega_0 C}{3 R_{12}}} \quad \bar{I}_{12m} = \sqrt{\frac{P_m S_m}{3 R_{12} (1-S_m)}}$$

$$R_{12} = \frac{P_m \cdot S_m}{3(1-S_m) \cdot I_{12}^2}$$

$$R_{12} = Z S_m \text{ per } s_{cc} 1$$

$$R_{12} = \frac{V_{1m}^2 (1-s) \cdot S_m}{P_m}$$

$$R_{12} = \frac{P_e p_1}{3 I_{12}^2}$$

$$R_{12} = \frac{P_m \cdot S \Omega_0}{\Omega 3 I_{12}^2}$$

$$R_{12} = \frac{X - R_1 \log \varphi_{12}}{\log 12}$$

$$R_{12} = \frac{S_m R_s}{1-S_m} = \frac{S_m}{1-S_m} (R_t - R) \quad R_{1B} = \frac{2}{3} R_1$$

$$R = \frac{P_e P}{3 I_{12}^2}$$

$$Z \Rightarrow Z^2 + R_{12}^2 + 2 R_1 R_{12} = \frac{V_{1m}^2 R_{12}}{\Omega_0 \cdot C_0}$$

$$R = \frac{P_{cc}}{3 I_{cc}^2}$$

$$Z = \sqrt{R_1^2 + X^2} \quad X = \left(R_1 + \frac{R_{12}}{s}\right) \tan \varphi_{12}$$

$$\dot{Z}_t = \frac{V_{1m}}{\sqrt{3} I_{12m}} = Z_{1cc} + R_{12} \left(\frac{1-S_m}{S_m}\right) = \left(R_1 + R_{12}\right) + j X_1 + X_{12} + R_{12} \left(\frac{1-S_m}{S_m}\right)$$

$$\dot{Z}_{cc} = \frac{V_{1cc}}{\sqrt{3} I_{1m}}$$

$$R = Z_{1cc} \cos \varphi_{1cc}$$

$$X = Z_{1cc} \sin \varphi_{1cc}$$

$$Z = \frac{V_{1m}^2}{2 \Omega_0 C_H} - R_1$$

$$X = R_1 \tan \varphi_{12\omega}$$

$$X = \tan \varphi_{1cc} (R_1 + R_{12}) \quad Z_{1cc} = \frac{V_{1cc}}{\sqrt{3} I_{1cc}}$$

$$R_0 = \frac{Z_0}{\cos \varphi}$$

$$X_0 = \frac{Z_0}{\sin \varphi}$$

$$Z_0 = \frac{V_{1m}}{\sqrt{3} I_0}$$

$$X = \sqrt{\left(\frac{V_{1m}}{\sqrt{3}}\right)^2 - \left(R_1 + \frac{R_{12}}{s}\right)^2}$$

$$P_e = P_t + P_{ep1} + P_0$$

$$= \sqrt{3} V_{1m} \cdot I_{1m} \cdot \cos \varphi_{1m}$$

$$P_m = (1-s) P_t$$

$$P_m = C \cdot \frac{2\pi n}{60}$$

$$P_t = P_e - P_{ep1}$$

$$P_e = P_m + P_p$$

$$P_{\omega} = R_1 I_{12\omega}^2$$

$$P_m = 3 R_{12} \left(\frac{1-s}{s}\right) I_{12}^2$$

$$P_t = \frac{3 R_{12} \cdot I_{12}^2}{s}$$

$$P_{ep2} = \frac{s}{1-s} P_m$$

$$P_e = P_a \cos \varphi_1$$

addizionali

$$C_m = \frac{P_m}{2\pi n_m / 60}$$

$$C_{elettrom} = \frac{P_m}{2\pi n / 60}$$

$$C_H = \frac{V_{1m}^2}{2 \Omega_0 \cdot Z}$$

$$C_H = \frac{V_{1m}^2}{2 R_0 (R_1 + Z)}$$

$$C_a = \frac{V_{1m}^2 \cdot R_{12}}{\Omega_0 \left[\left(R_1 + R_{12}\right)^2 + X^2 \right]}$$

$$C = \frac{P_m}{\Omega_0} = \frac{P_m}{\Omega_0 (1-s)}$$

$$C = \frac{60 P_m}{2\pi n}$$

$$C = \frac{3 \cdot R_{12}}{s \Omega_0} \cdot I_{12}$$

$$= \frac{V_{1m}^2 \cdot R_{12} \cdot \Omega_0}{\Omega_0 \cdot Z^2} = \frac{2\pi f}{P}$$

$$m_0 = \frac{60 f}{P}$$

$$m_m = m_0 (1-s_m)$$

$$f_s = S_m f$$

$$S_H = \frac{R_{12}}{Z}$$

$$S_{\text{addizionali}} = \frac{R_{12} + R_{12} a}{Z} = 1$$

$$R_{12} = \frac{m}{\text{addizionale } m} \cdot Z - R_{12}$$

$$s = 1 - \frac{P_m}{60 f}$$

$$\eta \% = \frac{P_m}{P_e}$$

$$S^2 = S_m + s(1-s) \frac{P_m}{P_m} = 0$$

$$\eta = \frac{P_m}{P_m + P_0 + P_{ep} + P_{addiz.}}$$

potenza perdute
corrispondente alla
potenze nelle correnti
MECCANICHE SIMILITUDINE

$$P_{ep} = 3 R I^2$$

potenza perdute
corrispondente alla
potenze nelle correnti
MECCANICHE SIMILITUDINE